DeviceNet Slave Device

CAN-2060D

User's Manual

Warranty

Without contrived damage, all products manufactured by ICP DAS are warranted in one year from the date of delivery to customers.

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1 Introduction

1.1 Overview

DeviceNet is one kind of the network protocols based on the CAN bus and mainly used for the embedded network of the machine control, such as industrial machine control , aircraft engines monitoring, factory automation, medical equipments control, remote data acquisition, environmental monitoring, and packaging machines control, etc.

CAN-2060D complies with DeviceNet specification Volume I/II, Release 2.0. Users can access digital I/O status and configure settings through the DeviceNet EDS file. This module features 4-channel isolated sink/source inputs and 4-channel relay outputs (Form A (SPST-NO)). It is suitable for various applications, including PNP, NPN, TTL, and relay contacts. If you have an ICP DAS DeviceNet master device, you can quickly establish a DeviceNet network to meet your needs.



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1.2 Hardware Specifications

Digital Output:

- Output Channels: 4 (Source)
- Resistive Load : 5A/30 VDC ，5A/250 VAC.
- Insulation Resistance: 1,000MΩs at 500 VDC.
- Output Type: Form A (SPST-NO)
- Intra-module Isolation: 3750 Vrms
- Reaction Time:
  - Operate Time: 10ms max
  - Release Time: 5ms max
- ESD Protection: 4 kV Contact for each channel

Digital Input:

- Input Channels: 4 (Sink/Source).
- DI On Level: +3.5 ~ +30 V_{DC}.
- DI Off Level: +1V_{DC} Max.
- Input Impedance: 3 kΩ, 0.3 W.
- Intra-module Isolation: 3750 Vrms
- Response Time: At least 250 us.
- ESD Protection: 4 kV Contact for each channel

Others:

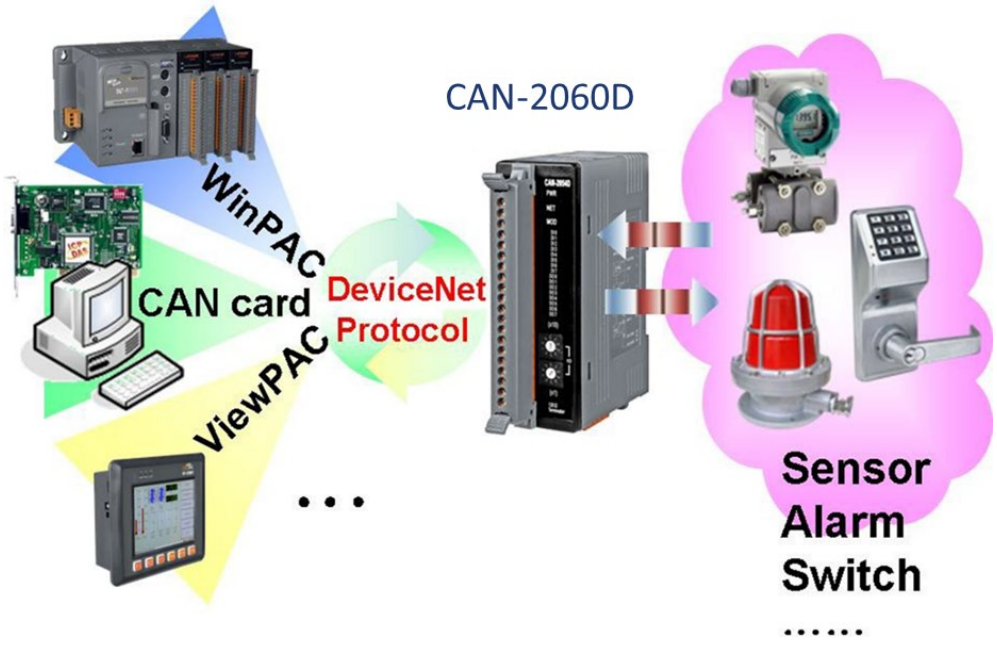
- DeviceNet Status: 3 LEDs for PWR / NET / MOD.
- Terminator Resister: 1 LED as terminator resister indicators
- DI LED：8 LEDs as digital input indicators.
- DO LED：8 LEDs as digital output indicators.
- Power Supply: Unregulated +10 ~ +30 VDC.
- Power Consumption: 1.5 W
- Operating Temperature: -25 ~ 75 ℃.
- Storage Temperature: -30 ~ 80 ℃.
- Humidity: 10 to 90% RH, Non-condensing..
- Dimensions: 33 mm x 99 mm x 78 mm (W x L x H) .

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1.3 Features

- DeviceNet general I/O slave devices.
- Comply with DeviceNet specification Volume I, Release 2.0 & Volume II, Release 2.0, Errata 5
- Group 2 Only Server (non UCMM-capable)
- Support Predefined Master/Slave Connection Set.
- Connection supported:
  - 1 connection for Explicit Messaging
  - 1 connection for Polled I/O
  - 1 connection for Bit-Strobe I/O connection
- Support DeviceNet heartbeat and shutdown messages
- Provide EDS file for standard DeviceNet master interface.
- NET, MOD and PWR Led indictors

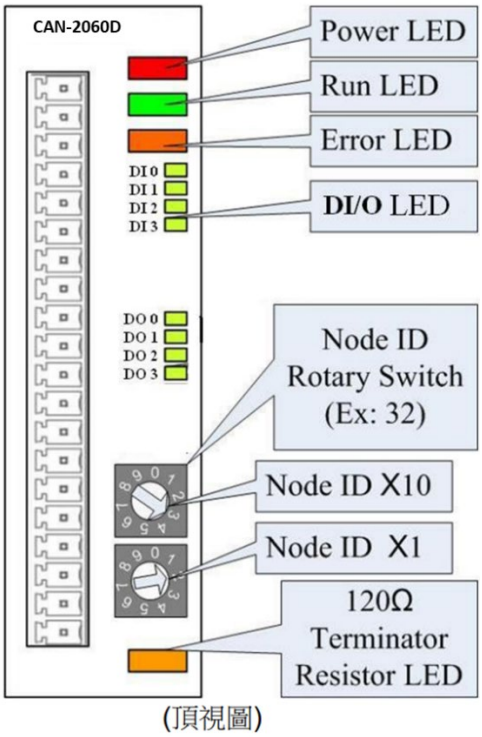
1.4 Application



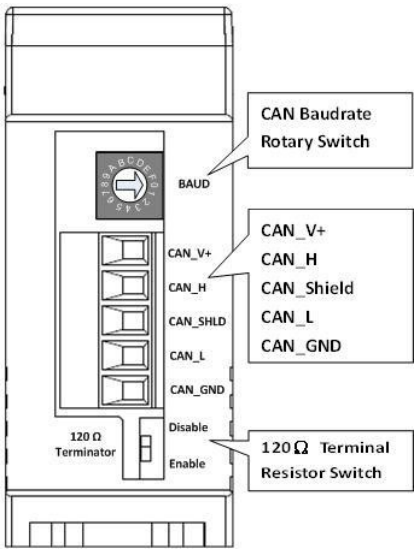
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2 Hardware

2.1 Structure



(Top View)

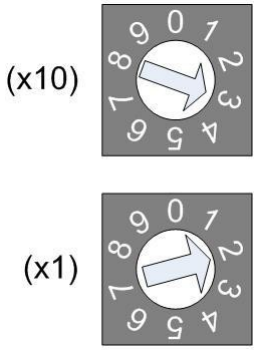


(Bottom View)

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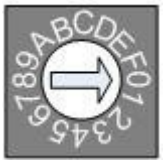
2.2 Node ID & Baud Rate Rotary Switch

The rotary switches of node ID configure the node ID of CAN-2060D module. These two switches are for the tens digit and the units digit of the node ID. The node ID value of this demo picture is 32.



Node ID rotary switch

The rotary switch for baud rate handles the CAN baud rate of CAN-2060D module. The relationship between the rotary switch value and the practical baud rate is presented in the following table.



Baud rate rotary switch

Rotary Switch Value	Baud rate (kbps)
0	125
1	250
2	500

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2.3 LED Description

PWR LED

The CAN-2060D needs the power of 10 ~ 30 VDC. Under a normal connection, a good power supply and a correct voltage selection, as the unit is turned on, the LED will light up in red.

NET LED

The NET LED indicates the current status of the DeviceNet communication link.

condition	status	indicates
Init Off	Off line	Device is not online
Off	Connection timeout	I/O connection timeout
Flashing	On line	Device is on line, but not communicating
Init solid	Link failed	(Critical) Device has detected an error that has rendered it incapable of communicating on the link; for example, detected a duplicate node address or network configuration error
Solid	On line, communicating	Device is online and communicating

MOD LED

This LED provides the devices status. It indicates whether or not the device is operating properly.

condition	status	indicates
Off	Normal	
Solid	Critical fault	Device has unrecoverable fault.
Flashing	Non_critical fault	Device has recoverable fault to recover. If users want to fix the problem, reconfiguring device's MAC ID or resetting device may work.

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Terminal Resistor LED

When enable the 120Ω terminator resistor, the LED will be turned on.

DO LED

If the DO LED is turned on, it means that the corresponding DO channel is active.

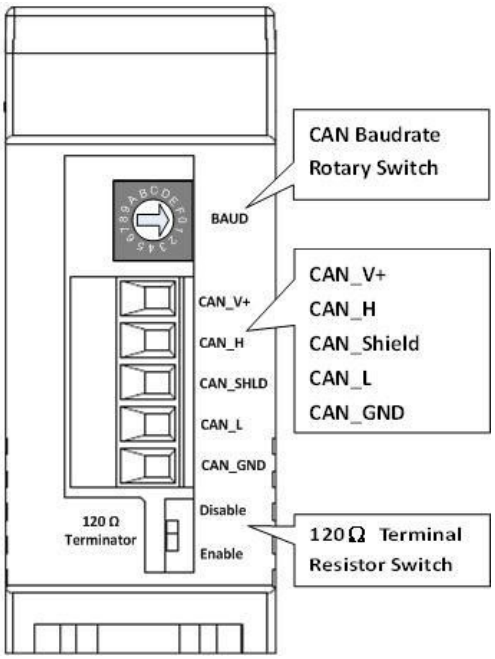
DI LED

If the DI LED is turned on, it means that the channel of DI is receiving an ON-Voltage-Level digital signal.

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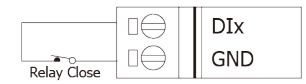
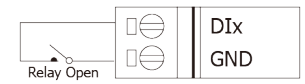
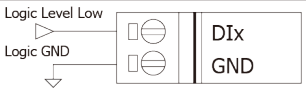
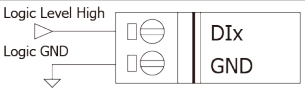
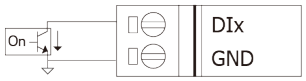
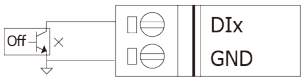
2.4 PIN Assignment

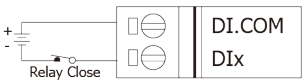
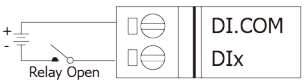
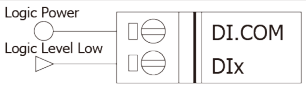
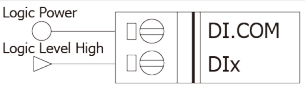
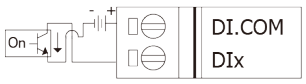
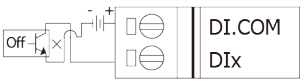
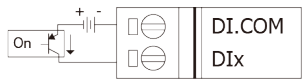
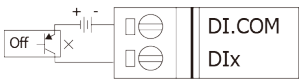
Terminal No.	Pin Assignment
01	DI.COM
02	DI0
03	DI1
04	DI2
05	DI3
06	GND
07	
08	NO0
09	COM0
10	NO1
11	COM1
12	NO2
13	COM2
14	NO3
15	COM3
16	
17	
18	
19	
20	

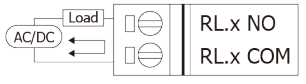
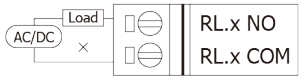


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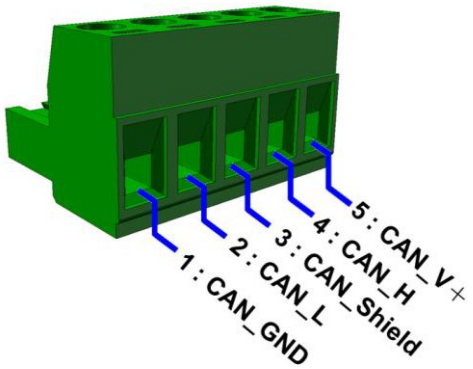
2.5 Wire Connection

Input Type Dry Contact	ON State LED ON	OFF State LED OFF
Relay Contact	Relay ON	Relay Off
		
TTL/CMOS Logic	Voltage > 3.5V	Voltage > 1V
		
Open Collector	Open Collector On	Open Collector Off
		

Input Type Dry Contact	ON State LED ON	OFF State LED OFF
Relay Contact	Relay ON	Relay Off
		
TTL/CMOS Logic	Voltage > 3.5V	Voltage < 1V
		
NPN Output	Open Collector On	Open Collector Off
		
PNP Output	Open Collector On	Open Collector Off
		

Output Type	ON State LED ON	OFF State LED OFF
Relay	Relay ON	Relay Off
		

5-pin screw terminal block



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3 DeviceNet Profile Area

This section describes the detailed functions for each object class that is implemented in the CAN-2060D DeviceNet network.

3.1 DeviceNet Statement of Compliance

General Device Data

Device Information	Description
Version Description of DeviceNet Specification	Volume I, Release 2.0 & Volume II, Release 2.0
Vendor Name	ICP DAS
Device Profile Name	CAN-2060D
Production Revision	1.1

DeviceNet Physical Conformance Data

Item	Description
LED Support	Yes
MAC ID Setting	Switch (0 ~ 63)
Default MAC ID	1
Communication Baud Rate Setting	Switch (125, 250, 500 kbps)
Default Baud Rate	125 kbps
Predefined Master/Slave Connection Set	Group 2 Only Server

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3.2 Identity Object (Class ID: 0x01)

This object provides the identification of and general information about the device

Class Attribute (Instance ID=0)

Attribute ID	Attribute name	Data Type	Method	Value
0x01	Revision	UINT	Get	0001
0x02	Max Instance	UINT	Get	1

Class Service

Service Code	Service name	Support
0x0E	Get_Attribute_Single	Yes

Instance Attribute (Instance ID=1)

Attribute ID	Description	Method	DeviceNet Data Type	Value
1	Vendor	Get	UINT	803
2	Product type	Get	UINT	0x00
3	Product code	Get	UINT	0x702
4	Major. Minor of firmware version	Get	Struct of USINT USINT	1.1
5	Status	Get	WORD	-
6	Serial number	Get	UDINT	1
7	Product name	Get	Short_String	CAN-2060D
10	Heartbeat Interval	Get/Set	USINT	0(default)

Instance Service

Service Code	Service name	Support
0x0E	Get_Attribute_Single	Yes
0x10	Set_Attribute_Single	Yes
0x05	Reset	Yes

Note: Use the Instance Service 0x05 will reboot the device.

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3.3 Connection Object (Class ID:0x05)

This section presents the externally visible characteristics of the Connection Objects associated with the Predefined Master/Slave Connection Set within slave devices.

The default IO connection path is as follow

Connection Path	Class ID	Instance ID	Attribute ID
Poll Produced	0x04	0x64	0x03
Poll Consumed	0x04	0x65	0x03
Bit Strobe Produced	0x04	0x64	0x03
Bit Strobe Consumed	0x04	0x65	0x03

Connection Instance ID	Description
1	References the Explicit Messaging Connection into the Server
2	References the Poll I/O Connection
3	References the Bit–Strobe I/O Connection

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3.4 Assembly Object (Class ID: 0x04)

The Assembly Object binds attributes of multiple objects, which allows data to or from each object to be sent or received over a single connection. Assembly objects can be used to bind input data or output data. The terms of ”input” and ”output” are defined from the network’s point of view. An input will produce data on the network and an output will consume data from the network

Class attribute (Instance ID=0)

Attribute ID	Attribute name	Data Type	Method	值 Value
0x01	Revision	UINT	Get	1
0x02	Max Instance	UINT	Get	0x02

Class service

Service Code	Service name	Support
0x0E	Get_Attribute_Single	Yes

Instance ID

Instance ID	OUTPUT	INPUT
0x64		Get DI value
0x65	Set DO value	Get DO value

Contents of Each Assembly Object Instance

Instance ID	Description	Type	Method	Default Value
0x64	Channel 0 ~ 3 DI value	USINT	Get	0x00
0x65	Channel 0 ~ 3 DO value	USINT	Get/Set	0x00

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Parameter description of Assembly Object Instance

Instance ID	Data Range	Parameter Description
0x64	0x00 ~ 0x0F	Bit 0 => channel 0 DI value Bit 1 => channel 1 DI value … Bit 3 => channel 3 DI value
0x65	0x00 ~ 0x0F	Bit 0 => channel 0 DO value Bit 1 => channel 1 DO value … Bit 3 => channel 3 DO value

Note: x is channel number of module

Instance attribute (Instance ID=0x64~0x65)

Attribute ID	Description	Method	DeviceNet Data Type	Value
0x03	資料	Get/Set	OUTPUT/ INPUT	Dependent on instance ID

Instance service

Service Code	Service name	Support
0x0E	Get_Attribute_Single	Yes
0x10	Set_Attribute_Single	Yes

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3.5 Application Object1 (Class ID: 0x64)

Application objects are the interfaces between an application and the DeviceNet Layer. The attributes of application Objects contain the data for the application, which are accessed and exchanged via DeviceNet. DeviceNet accesses application data by invoking read and write functions. These functions need to be provided by an Application Object. DeviceNet provides Get_Attribute_Single and Set_ Attribute_Single to read and write CAN-2060D module.

Application Object1 defines pulse output channels and digital input channels configuration.

Class attribute (Instance ID=0)

Attribute ID	Attribute name	Data Type	Method	Value
0x01	Revision	UINT	Get	1
0x02	Max Instance	UINT	Get	0x06

Class service

Service Code	Service name	Support
0x0E	Get_Attribute_Single	Yes

Instance attribute (Instance ID=0x01)

Attribute ID	Description	Method	Data Type	Default Value
0x01	DI value	Get	USINT	0x00
0x02	DO value	Get/Set	USINT	0x00
0x03	DO power on value	Get/Set	USINT	0x00
0x04	DO safe value mask	Get/Set	UDINT	0x00
0x05	DO safe value	Get/Set	USINT	0x00
0x06	Save all Configuration to EEPROM	Set	USINT	-

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Parameter description of Application Object1 attributes

Attribute ID	Data Range	Parameter Description
0x01	0x00 ~ 0x0F	Bit 0 => channel 0 DI value Bit 1 => channel 1 DI value … Bit 3 => channel 3 DI value
0x02	0x00 ~ 0x0F	Bit 0 => channel 0 DO value Bit 1 => channel 1 DO value … Bit 3 => channel 3 DO value
0x03	0x00 ~ 0x0F	Bit 0 => channel 0 DO power on value Bit 1 => channel 1 DO power on value … Bit 3 => channel 3 DO power on value
0x04	0x00 ~ 0x0F	Bit 0 => channel 0 DO safe value mask Bit 1 => channel 1 DO safe value mask … Bit 3 => channel 3 DO safe value mask Bit value=1 => apply safe value setting Bit value=0 => apply DO output value
0x05	0x00 ~ 0x0F	Bit 0 => channel 0 DO safe value Bit 1 => channel 1 DO safe value … Bit 3 => channel 3 DO safe value
0x06	0x01: Use default configuration 0x02: Save all Configuration to EEPROM	0x01: After restarting the device, configuration will become factory setting. 0x02: Save all channels configuration into EEPROM

Instance service

Service Code	Service name	Support
0x0E	Get_Attribute_Single	Yes
0x10	Set_Attribute_Single	Yes

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4 Application

Application Object1 (Class ID:0x64) lists all the parameters of the module. Each Instance ID is corresponding to the different cahnnels. By using “Set/Get Attribute Single” service, user can read/write the parameters of each channel.

Example 1:

Set DO output value.

(Class ID: 0x64, Instance ID: 0x01, Attribute ID 0x02).

If the node ID of the CAN-2060D is 1, and the master (ID: 0x0A) has completed “Explicit” connection with the device. By setting the value of Attribute ID 0x02 to 0x0F, you can set the DO0, DO1, DO2, and DO3 to turn ON and others to turn OFF.

IDENTIFIER BITS											RTR	Data Length	8-byte Data (byte) (HEX)							
		Destination MAC ID																		
10	9	8	7	6	5	4	3	2	1	0			0	1	2	3	4	5	6	7
1	0	0	0	0	0	0	1	1	0	0	0	6	0A	10	64	01	02	FF	--	--

Master → **Slave (CAN-2060D)**

IDENTIFIER BITS											RTR	Data Length	8-byte Data (byte) (HEX)							
		Source MAC ID																		
10	9	8	7	6	5	4	3	2	1	0			0	1	2	3	4	5	6	7
1	0	0	0	0	0	0	1	0	1	1	0	2	0A	90	--	--	--	--	--	--

Master ← **Slave (CAN-2060D)**

Set the value 0x0F to the Application Object1 with Instance ID 0x01 and Attribute ID 0x02. After sending the “Set Attribute Single”, the slave device will response 0x90 to mean that the setting is OK. Then the DO0, DO1, DO2, and DO3 will be turned ON and others are turned OFF.

Via changing the Attribute ID of the Application Object, user can set other parameters of this device.

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Example 2:

Get DI data (Class ID: 0x64, Instance ID: 0x01, Attribute ID 0x01).

If the node ID of the CAN-2060D is 1, and the master (id: 0x0A) has completed “Explicit” connection with the device. By getting the value of the object with attribute ID 0x01, you can get the channel 0 ~ 3 of the DI data.

IDENTIFIER BITS											RTR	Data Length	8-byte Data (byte) (HEX)							
		Destination MAC ID																		
10	9	8	7	6	5	4	3	2	1	0			0	1	2	3	4	5	6	7
1	0	0	0	0	0	0	1	1	0	0	0	5	0A	0E	64	01	01	--	--	--

Master → **Slave (CAN-2060D)**

IDENTIFIER BITS											RTR	Data Length	8-byte Data (byte) (HEX)							
		Source MAC ID																		
10	9	8	7	6	5	4	3	2	1	0			0	1	2	3	4	5	6	7
1	0	0	0	0	0	0	1	0	1	1	0	3	0A	8E	0F	--	--	--	--	--

Master ← **Slave (CAN-2060D)**

Get the value of Application Object1 with Instance ID 0x01 and Attribute ID 0x01. After sending the “Get Attribute Single”, the slave device response the DI data (0x0F) at byte 2. The value 0x0F means that the status of DI3, DI2, DI1 and DI0 are turned on and others are turned off.

By changing the Instance ID and Attribute ID of the Application Object, you can get other parameters of this device.

The Attribute 0x03 of Application Object1 can control the DO power on value of each channel. After setting this attribute, the DO channels will output DO power on value when booting up.

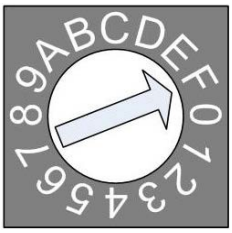
Attribute 0x04 and 0x05 of Application Object1 are used for safe value configuration when “Explicit Message Timeout” error occurs. When setting the channel selection value of the Attribute ID 0x04 to “0x1”, the safe value of Channel 0 will be active. If the value is set to 0x4, it means that the safe value of the channel 2 is active. Afterwards, you can configure the output safe value of this channel by setting the value of Attribute ID 0x05. When setting the Attribute ID 0x04 to “0x1” and Attribute ID 0x05 to “0x1”, the channel 0 will turn ON while the error occurs.

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5 Firmware Update

Step 1: Set Module to “Bootloader” mode

Set Module to “Bootloader” mode (set baud rate to 0xF). Then power on the module. After power on, the module’s led (PWR, NET, MOD) will be flashed at the same time. It means that the module have entered into “Bootloader” mode.



Baud Rate Rotary Switch

Step 2: Get Module firmware

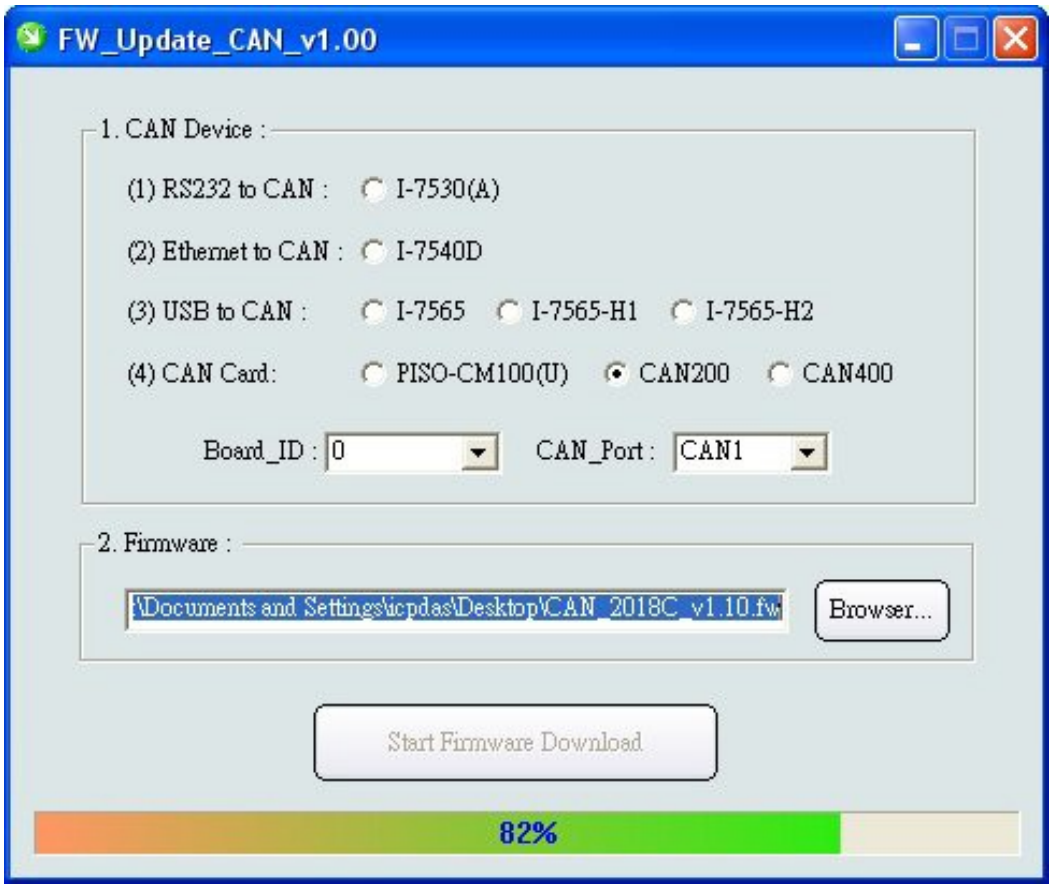
Module firmware can be downloaded from following link:
https://www.icpdas.com/en/download/show.php?num=1935&model=CAN-2060D

Step 3: Run FW_Update_CAN Utility

FW_Update_CAN Utility can be downloaded from following link
https://www.icpdas.com/en/download/show.php?num=1914&model=CAN-2060D

Run FW_Update_CAN Utility

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[1] CAN Device:

The below ICP DAS CAN products are supported by FW_Update_CAN utility for firmware update.

(1) RS232 to CAN **:** I-7530

(2) Ethernet to CAN **:** I-7540D

(3) USB to CAN **:** I-7565, I-7565-H1, I-7565-H2

(4) CAN Card**:** PISO-CM100(U), PISO-/PCM-/PEX-CAN200 / CAN400

Before firmware update, users need to set the below parameters.

(1) Select CAN hardware interface

(2) Set Dev_Port or Board_ID

(3) Set CAN_Port" number

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[2] Download Firmware :

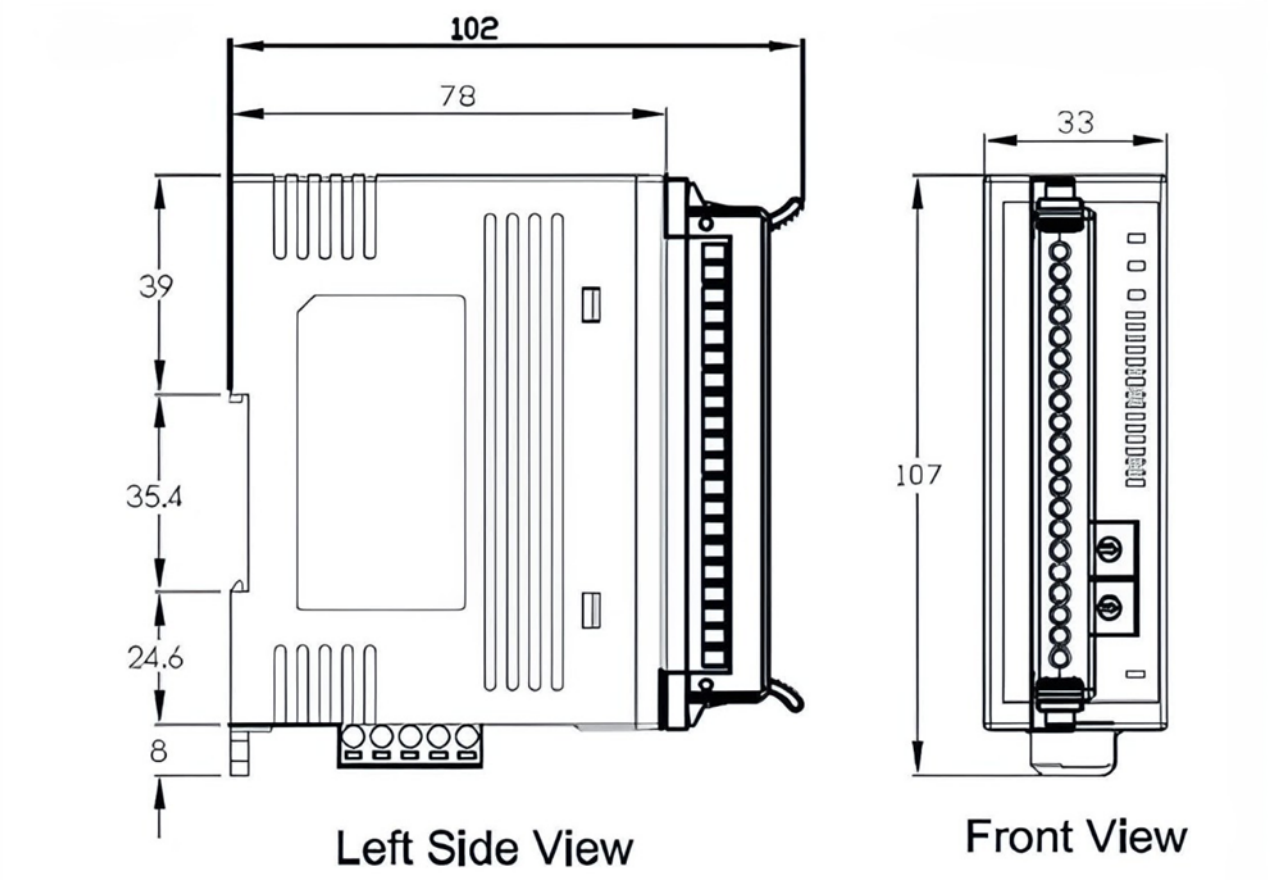
(1) Click “**Browser**…” button to choose firmware file, can_2060d_vX.X.fw.

Click “**Start Firmware Update**” button to start firmware update and it will show the total percentage of firmware update in progress bar. After the firmware update finished, it will show the “Firmware Update Success !!” message.



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Appendix A: Dimension



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